

XL1195

### **Features**

- Built in dynamic impedance matching function
- Built in decoding error correction function
- Built in decoding signal correction function
- Built in hardware codec
- Enhanced anti-interference ability
- Support multiple network topologies
- Support adjusting load balancing time
- Simple circuit design
- High reliability
- Communication speed adaptation from 9.6kbps to 57.6kbps
- Operating temperature -40°C~125°C
- Available in SOP16 package

### **Applications**

- Central Air Conditioner
- HVAC
- Smart Home
- Remote Monitoring and Sensing

### **General Description**

The XL1195 conforms to the HBS(Home Bus) specification, built in dynamic impedance matching function, decoding error correction function, decoding signal correction function, adjusting load balancing time, and has functions for the reception and transmission of data. AMI is adopted for the waveforms of signals handled by the transmission and reception units, designed for connection to twisted-pair lines. The IC can be driven by a single 5V power supply, and incorporates an output transistor to reduce the number of external components required.

XL1195 is a special hardware encoding and decoding chip for DC carrier communication. It supports DC carrier and nonpolar connection. It has flexible bus topology and strong anti-interference ability. It can communicate while powered by twisted pair cablies. The communication distance can reach 1000m. It has built-in protection module, simple peripheral circuit and high reliability.



Figure 1. Package Type of XL1195



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# Pin Configurations

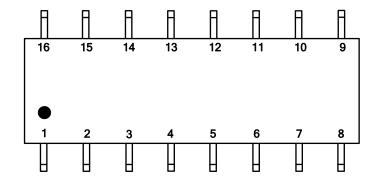


Figure 2. Pin Configuration of XL1195 (Top View)

### Table 1 Pin Description

Pin Number	Pin Name	Description
1	DATA OUT(A)	Data output pin A.
2	DATA OUT(B)	Data output pin B.
3	BC2	Boost capacitor pin 2.
4	BC1	Boost capacitor pin 1.
5	RESET	Reset control pin.
6	DATA IN	Data input pin.
7	PWM	PWM signal pin.
8	RT	Dynamic load balancing time adjustment pin. Connect an external resistor to the GND pin and connect it to the VCC pin when not in use.
9	OUT(A)	Bus signal transmission pin A.
10	OUT(B)	Bus signal transmission pin B.
11	VCC	Supply voltage input pin.
12	NC	No connected.
13	GND	Ground pin.
14	RD	Signal correction pin. Connect to GND through a resistor and adjust the duty cycle of DATA OUT (B).
15	IN(2)	Bus signal receiving pin 2.
16	IN(1)	Bus signal receiving pin 1.



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### **Function Block**

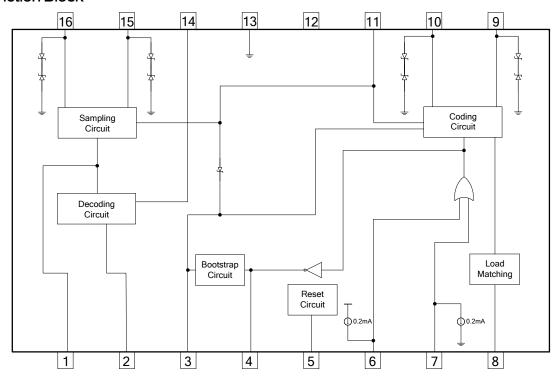


Figure 3. Function Block Diagram of XL1195

### **Typical Application Circuit**

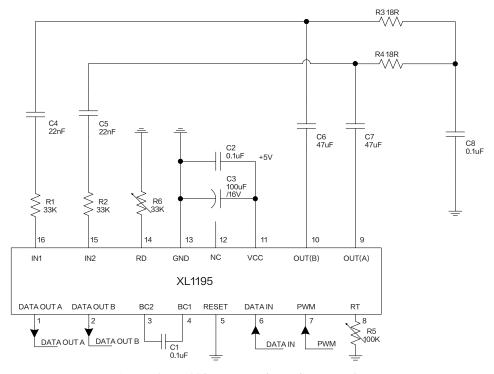


Figure 4. XL1195 Typical Application Circuit



HBS-Compatible Driver and Receiver Monolithic IC	XL1195

### **Ordering Information**

Order Information	Marking ID	Package Type	Eco plan	Packing Type Supplied As
XL1195	XL1195	SOP16	RoHS & HF	2500 Units on Tape & Reel

### Absolute Maximum Ratings (T<sub>A</sub>=25℃)

Parameter	Symbol	Value	Unit
Operating power supply voltage (VCC)	V <sub>CCOP1</sub>	4.5 ~ 5.5	V
Recommended power supply voltage range	V <sub>CCOP2</sub>	4.75 ~ 5.25	V
Power supply voltage (VCC)	Vccmax.	-0.3~7	V
Pin3 voltage	V <sub>PIN3</sub>	-0.3~10	V
Other pins voltage	V	-0.3~VCC	V
Power Dissipation	P <sub>D</sub>	450	mW
Operating Junction Temperature	TJ	<b>−40 ~ 125</b>	${\mathbb C}$
Storage Temperature	Тѕтѕ	<b>−40 ~ 125</b>	${\mathbb C}$
Lead Temperature (Soldering, 10 sec)	T <sub>LEAD</sub>	260	$^{\circ}$
ESD (HBM)(PIN9,PIN10)		>8000	V
ESD (HBM)(Other PINs)		>3000	V

**Note1:** Stresses greater than those listed under Maximum Ratings may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operation is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

**Note2:** Pins 9,10,15 and 16 have built–in bus burr voltage absorption circuit. They can absorb positive and negative burr voltage, and the clamping voltage is designed to be positive and negative 7.2V.



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### XL1195 Electrical Characteristics

VCC=5V, GND=0V,  $T_A$ =25°C;  $F_{PING}$ =9.6KHz(Duty=50%),  $F_{PIN7}$ =19.2KHz(Duty=50%), PIN5=0V, R5=100K $\Omega$ , R6=33K $\Omega$ , RL=36 $\Omega$ , System parameters test circuit figure4, unless otherwise specified.

Parameters	Symbol	Test Condition Min.		Тур.	Max.	Unit
Power supply current 1	ICCO	PIN5=5V		10		mA
Power supply current 2	ICCON1	PIN7=0V	N7=0V			mA
Power supply current 3	ICCON2			40		mA
Transmission output voltage	V <sub>TO</sub>	Both pins 9 and 10	3.8	4.2	4.6	$V_{P-P}$
Transmission waveform symmetry	V <sub>TR</sub>	V <sub>TO</sub> 1/V <sub>TO</sub> 2	0.75	1.0	1.25	
Reception Sensitivity	$V_{ extsf{RS}}$			0.75		$V_{P-P}$
Noise resistance	$V_{RN}$	Level at which no errors are output	0.55			$V_{P-P}$
Input impedance	R <sub>IN</sub>	Both pins 15 and 16	25	36	46	ΚΩ
Transmission delay time 1	T <sub>d</sub> 1	cf. transmit/receive waveform diagrams		0.6		uS
Transmission delay time 2	T₀2	cf. transmit/receive waveform diagrams		2.7		uS
Transmission delay time 3	T <sub>d</sub> 3	cf. transmit/receive waveform diagrams		3.3		uS
Reception output H voltage	$V_{ROH}$		4.5			V
Reception output L voltage	$V_{ROL}$				0.5	V
H level input voltage 1	V <sub>LIH</sub>	PIN6	2.4			V
L level input voltage 1	V <sub>LIL</sub>	PIN6			0.6	V
H level input current 1	I <sub>LIH</sub>	V <sub>DATAIN</sub> =2.4V			10	uA
L level input current 1	ILIL	V <sub>DATAIN</sub> =0.4V			-400	uA
H level input voltage 2	V <sub>LIH</sub>	PIN7	2.4			V
L level input voltage 2	V <sub>LIL</sub>	PIN7			0.6	V
H level input current 2	Іпн	V <sub>PWM</sub> =2.4V			400	uA
L level input current 2	I <sub>LIL</sub>	V <sub>PWM</sub> =0.4V			400	uA
Bootstrap output H voltage	$V_{BR}$		7.5	8.0		V



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### **Timing Chart**

### **Data Transceiver Timing Chart**

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### Transmission delay time

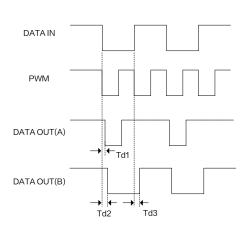


Figure 5. XL1195 Timing diagram

**Note 1:** The peripheral components in the block diagram are the constants for Data Rates 9.6kbps. If the data rates is low, larger values should be chosen for the coupling capacitors between the receive and transmit pins and the bus line and for the capacitor connecting pins 3 and 4.

**Note 2:** The Pin 7 of the chip can access the Data Rates 19.2kbps square wave signal, Realize Pin6 signal (Data Rates 9.6kbps) and Pin7 signal synchronization (the Pin 6 data signal is synchronized at the falling edge of the Pin 7 square wave signal) to ensure that the hardware coding is correct.

**Note 3:** Pin1 of the chip outputs the demodulated 19.2kbps signal, and Pin2 outputs the decoded 9.6kbps signal (equivalent to doubling the low–level time of Pin1 output signal).

**Note 4:** The current limit function is built into this IC. There is a possibility that IC generates heat when the output terminal is short. However, the characteristic changes depending on the substrate condition. Please evaluate IC in the set.

**Note 5:** The ceramic capacitor should be placed closer the VCC and GND pins to eliminate noise. Increase the grounding vias to decrease the Parasitic parameter.



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### **Function Description**

### Dynamic impedance matching function

XL1195 has a built-in dynamic impedance matching function to improve the bus signal. When the rising edge of the internal coding signal is detected, the built-in matching resistors are briefly connected in parallel to PIN9 and PIN10, and PIN8 is connected to GND through a resistor to adjust the dynamic impedance matching time. This function can be turned off by connecting PIN8 to VCC.

### Decoding signal correction function

XL1195 has a decoding signal correction function. In the case of long-distance communication, the bus parasitic parameter is large, and the signal transmitted on the bus is affected by the bus parasitic parameter and will turn to a slower level in the middle of the level, resulting in insufficient high level pulse width of the chip's decoding signal, which affects the quality of communication. PIN14 is connected to GND through a resistor, and the resistor value can be adjusted to compensate for the high level pulse width of the PIN2.

### Decoding error correction function

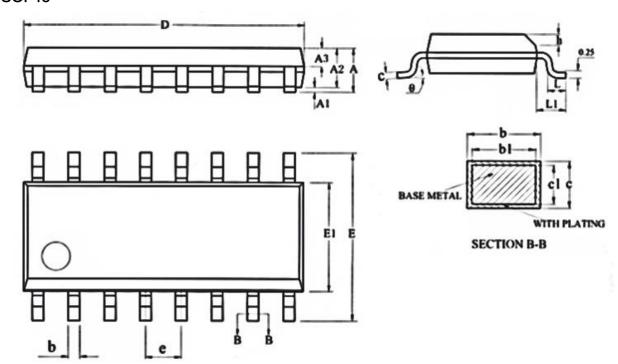
XL1195 has built-in decoding and error correction function. It can solve errors caused by bus interference or oscillation, improve decoding accuracy and stability.



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# Package Information

## SOP16



Symbol	Dimensions In Millimeters			Dimensions In Inches		
	Min.	Nom.	Max.	Min.	Nom.	Max.
Α	-	-	1.75	_	_	0.069
A1	0.10	0.15	0.25	0.004	0.006	0.010
A2	1.30	1.40	1.50	0.051	0.055	0.059
A3	0.55	0.65	0.75	0.022	0.026	0.030
b	0.33	-	0.51	0.013	_	0.020
b1	0.35	0.40	0.45	0.014	0.016	0.018
С	0.17	-	0.25	0.007	_	0.010
c1	0.19	0.20	0.21	0.007	0.008	0.009
D	9.80	10.00	10.20	0.386	0.393	0.402
Е	5.80	6.00	6.20	0.228	0.236	0.244
E1	3.80	3.90	4.00	0.150	0.154	0.157
е		1.27 REF.			0.050 REF.	
h	0.25	_	0.50	0.010		0.020
L	0.40	_	1.27	0.015	_	0.050
L1	1.05 REF.			0.041 REF.		
θ	0°	_	8°	0°	_	8°



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